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example of this is the port direction registers on a PICmicro®MCU are set 1=Input 0=Output, whereas the H8 is 0=Input and 1=Output. The use of C in Microcontroller applications has been brought about by manufacturers providing larger program and RAM memory areas in addition to faster operating speeds.

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PIC microcontroller project book by John Lovine. Programming and customizing the PIC microcontroller by

Myke Predko. ... Programming a PIC Microcontroller Page 10 of 24 The last window in the Project Wizard is a summary of the options you have selected. If

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Robotics experiment with PIC microcontroller 5 Chapter 1 Part list of Robo-PICA and Introduce software tool  
1.1 Robo-PICA part list There are 2 groups : 1.1.1 Mechanical parts 1.1.2 Electronic parts 1.1.1 Mechanical parts Motor Gearbox â€“ Uses a 4.5V (9V max.) and 180 mA DC motor with a ratio of 48:1; torque 4kg/cm; comes with the mounting.

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